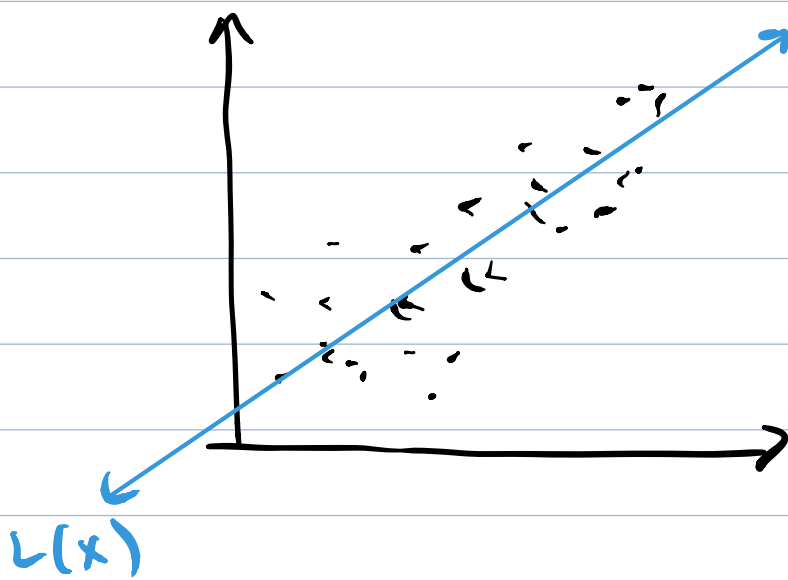


Mon, March 15

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Last time: WIS

Example #2: Segmented Least Squares  
Linear Regression:

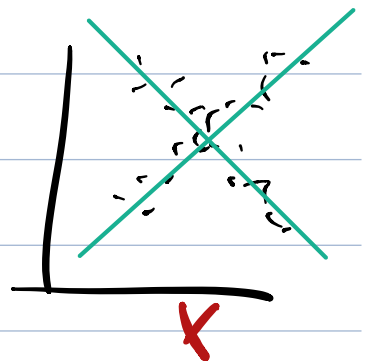
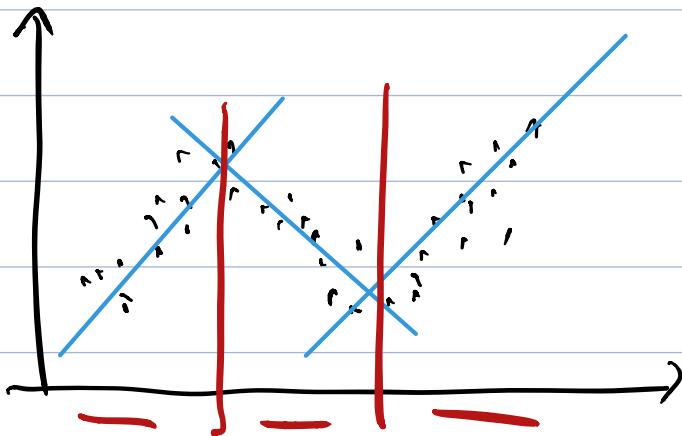


points  $(x_1, y_1) \dots (x_n, y_n)$

goal: minimize

$$\sum_{i=1}^n (L(x_i) - y_i)^2$$

Bad:



Segmented Least Squares:

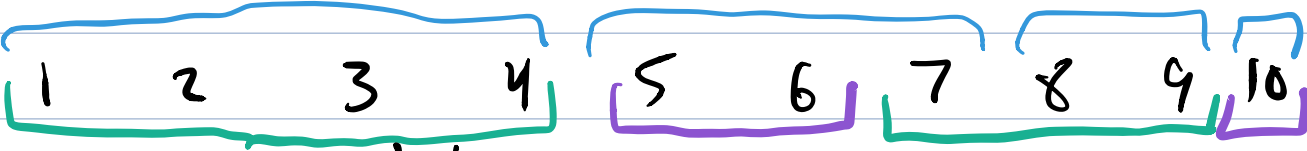
- Split the data points into  $k$  consecutive blocks

- Find the least squares line for each block separately
- Minimize: some combination of # of lines and the errors of each line

Score:  $C \cdot (\# \text{ of lines}) + \text{sum of errors of each line}$

where  $C > 0$  is a parameter that we can tweak to affect the optimal solution.

Search Space: all ways of splitting the points into consecutive blocks.

Ex:   
= 4 blocks

Each of these candidates corresponds to an ~~"integer partition"~~ "compositions"  
 $10 = 4 + 3 + 2 + 1$   
 $4 + 2 + 3 + 1$

The # of these is exponential.  $2^n$

# Dynamic Programming:

## Subproblems

(WIS: each new request is either  
in or out  
 $v_e + O(p(R_e))$  or  $O(R_{e-1})$ )

Each solution has:

- a final block of points  $p_i, \dots, p_n$
  - an optimal solution on  $p_1, p_2, \dots, p_{i-1}$
- $n=50$

Define  $e_{i,j}$  to be the least squares  
error for points  $p_i, p_{i+1}, \dots, p_j$ .  
 $O(i)$  to be the optimal score  
on  $p_1, \dots, p_i$ .

We want  $O(n)$ .

What is the cost of having the last  
block go  $p_i, \dots, p_n$ ?

$$\text{cost} = \underset{\substack{\uparrow \\ \text{error of last line}}}{e_{i,n}} + \underset{\substack{\uparrow \\ \text{optimal solution on } p_1, \dots, p_{i-1}}}{C} + O(i-1)$$

*cost per line*  $\rightarrow$

So, the optimal score for  $p_1, \dots, p_n$  is the one where  $i$  leads to a minimum cost.

$$\text{Recurrence: } \begin{cases} \sigma(0) = 0 \\ \sigma(j) = \min_{1 \leq i \leq j} (e_{i,j} + C + \sigma(i-1)) \end{cases}$$

$$\sigma(n) = \min_{1 \leq i \leq n} (e_{i,n} + C + \sigma(i-1))$$

$$= \min(e_{1,n} + C + \sigma(0), e_{2,n} + C + \sigma(1), \dots, e_{n,n} + C + \sigma(n-1))$$

1    2    3    4    5    6     $n=6$

one line

WIS: top-down

Better: bottom-up

```

memo = dict()
memo[0] = 0
compute  $e_{i,j}$  for all pairs  $i \leq j$ . all pairs  $O(n^2)$ 
for  $j = 1, \dots, n$ :
     $memo[j] = \min(e_{i,j} + C + memo[i-1],$  }  $O(n)$ 
                     $i = 1, \dots, j)$ 
return memo[n]

```

"iterative"

Runtime?  $O(n^2)$

The key to d.p. is figuring out what you need to know.

In SLS, we only need to know the optimal cost for each possible endpoint  $O(i-1)$ . The actual composition on  $P_1, \dots, P_{i-1}$  has no effect on the cost of adding the next block  $P_i, \dots, P_j$ . So we can forget it.

$C$  = cost per line